

# Lecture 2

# Vector analysis and calculus

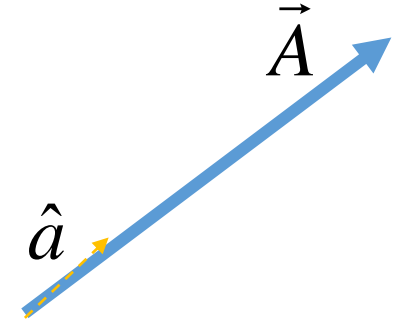
*Prepared by Dr. Gehan Sami*

# Vectors and Scalars

**Vector** : has both magnitude and direction in space as velocity, force, electric field

$$\vec{A} = |\vec{A}| \hat{a} = A \hat{a} = A_x(x, y, z) \hat{a}_x + A_y(x, y, z) \hat{a}_y + A_z(x, y, z) \hat{a}_z$$

$$|\vec{A}| = A = \sqrt{A_x^2 + A_y^2 + A_z^2} \quad \hat{a} = \frac{\vec{A}}{|\vec{A}|}, \quad |\hat{a}| = 1$$



**Scalar quantity** : has magnitude only as temperature, mass, volume,....etc.

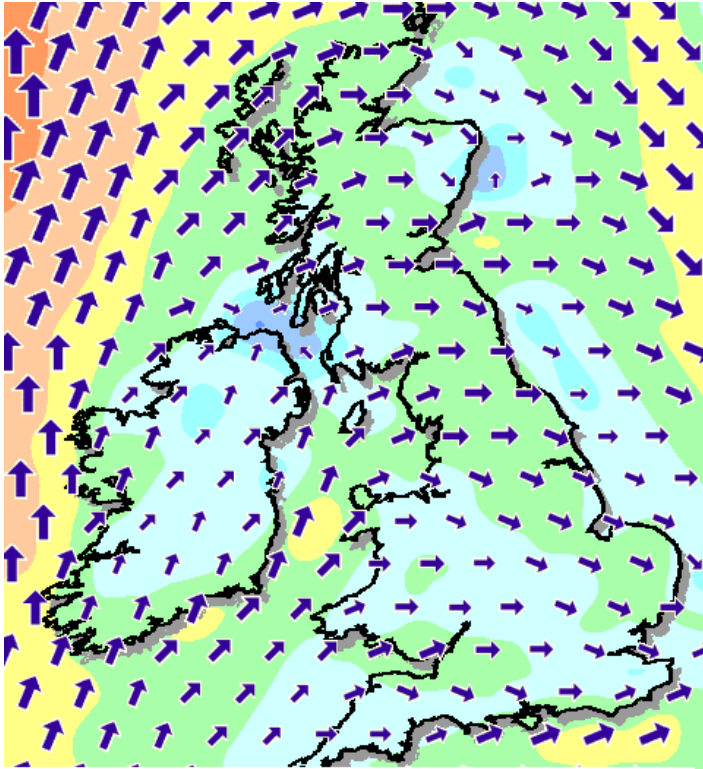
$$\vec{E} = E \hat{a}_x$$

Vector    scalar    unit vector

$$\vec{E}, \underline{E}$$

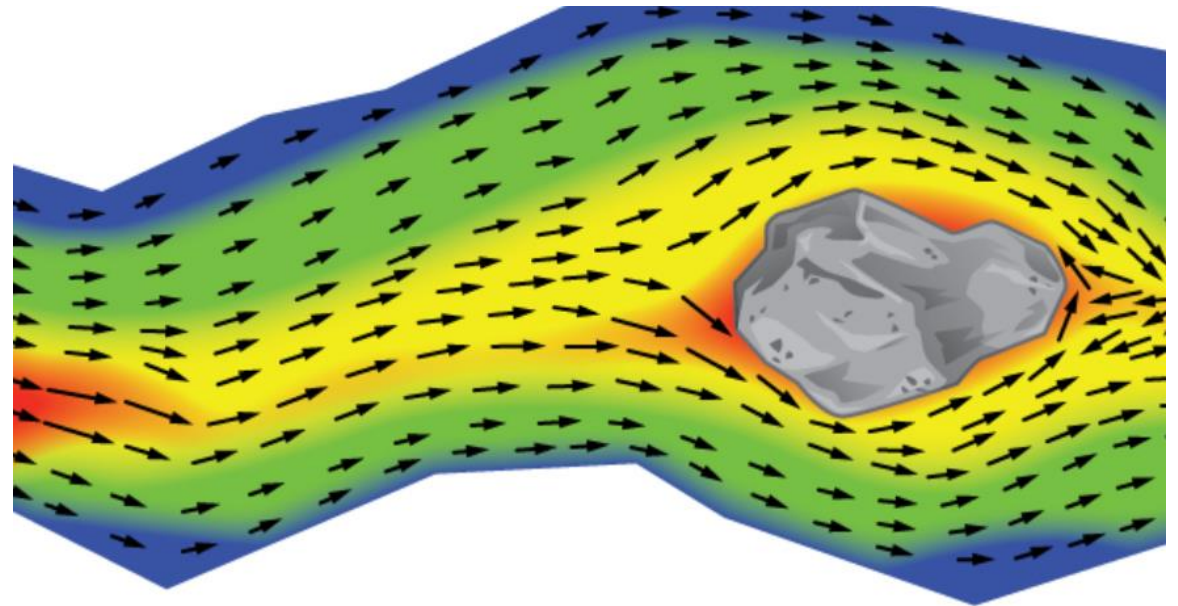
Other notation

## vector field examples



wind map

every point has a vector has magnitude (velocity of wind) and direction (of velocity).



water flow

The vector velocity field of water on the surface of a river shows the varied speeds of water.

## The Cartesian Coordinate System

source  $\vec{A} = (x_1, y_1, z_1)$ ,

observation point  $\vec{B} = (x_2, y_2, z_2)$

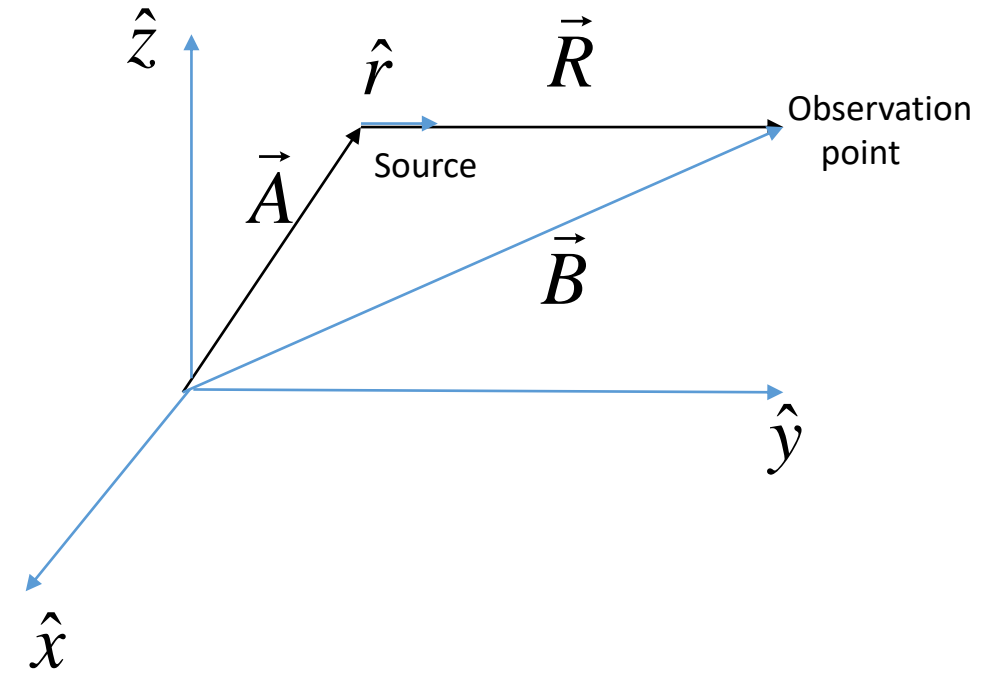
$$\vec{A} + \vec{R} = \vec{B} \rightarrow \vec{R} = \vec{B} - \vec{A}$$

$$\vec{R} = (x_2 - x_1, y_2 - y_1, z_2 - z_1)$$

$$= (x_2 - x_1)\hat{x} + (y_2 - y_1)\hat{y} + (z_2 - z_1)\hat{z}$$

distance between source and observation point

$$|\vec{R}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$



$$\vec{R} = |\vec{R}| \hat{r}$$

Direction from source  
To observation point

Distance between source  
and observation point

## Example 1.1

Specify the unit vector extending from the origin toward the point  $G(2, -2, -1)$ .

*Solution.* the vector extending from the origin to point  $G$ ,

$$\mathbf{G} = 2\mathbf{a}_x - 2\mathbf{a}_y - \mathbf{a}_z$$

the magnitude of  $\mathbf{G}$ ,

$$|\mathbf{G}| = \sqrt{(2)^2 + (-2)^2 + (-1)^2} = 3$$

the unit vector

$$\mathbf{a}_G = \frac{\mathbf{G}}{|\mathbf{G}|} = \frac{2}{3}\mathbf{a}_x - \frac{2}{3}\mathbf{a}_y - \frac{1}{3}\mathbf{a}_z = 0.667\mathbf{a}_x - 0.667\mathbf{a}_y - 0.333\mathbf{a}_z$$

**D1.1.** Given points  $M(-1, 2, 1)$ ,  $N(3, -3, 0)$ , and  $P(-2, -3, -4)$ , find: (a)  $\mathbf{R}_{MN}$ ; (b)  $\mathbf{R}_{MN} + \mathbf{R}_{MP}$ ; (c)  $|\mathbf{r}_M|$ ; (d)  $\mathbf{a}_{MP}$

*Ans.*  $4\mathbf{a}_x - 5\mathbf{a}_y - \mathbf{a}_z$ ;  $3\mathbf{a}_x - 10\mathbf{a}_y - 6\mathbf{a}_z$ ; 2.45;  $-0.1400\mathbf{a}_x - 0.700\mathbf{a}_y - 0.700\mathbf{a}_z$ ;

## Vector Multiplication:

The dot Product(Scalar Product)

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$$

← scalar

$$\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A} \quad \text{the result is scalar}$$

If:  $\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$

$$\vec{B} = B_x \hat{a}_x + B_y \hat{a}_y + B_z \hat{a}_z \rightarrow \vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

Notes:

*Vector dotted with itself is magnitude square*

$$\vec{A} \cdot \vec{A} = |\vec{A}|^2 = A^2$$

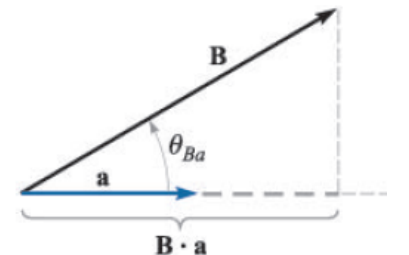
*any unit vector dotted with itself is unity*

$$\hat{a}_x \cdot \hat{a}_x = 1$$

*dot product find the component of vector in a given direction*

$$\vec{B} \cdot \hat{a} = |\vec{B}| \cos \theta_{Ba}$$

← Unit vector



## The Cross Product(Vector Product)

$$\vec{A} \times \vec{B} = |\vec{A}| |\vec{B}| \sin \theta \hat{n}$$

Result is vector perpendicular to A&B

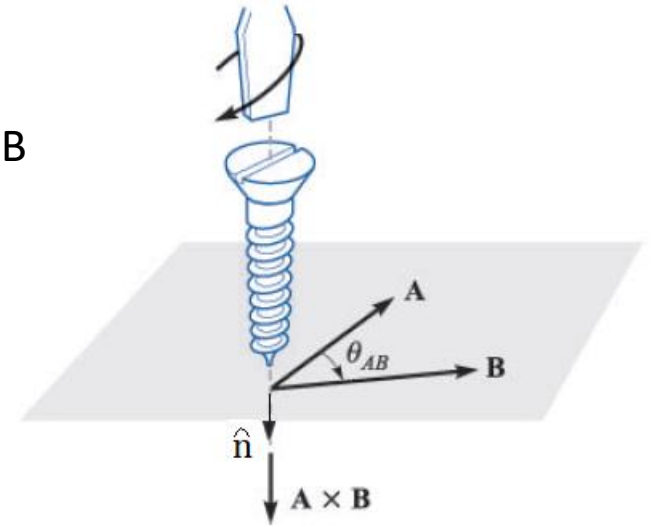
$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Notes:

$$\hat{a}_x \times \hat{a}_y = \hat{a}_z, \hat{a}_y \times \hat{a}_z = \hat{a}_x, \hat{a}_z \times \hat{a}_x = \hat{a}_y$$

$$\hat{a}_x \times \hat{a}_x = \hat{a}_y \times \hat{a}_y = \hat{a}_z \times \hat{a}_z = 0$$

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}, \quad \vec{A} \times (\vec{B} + \vec{C}) = \vec{A} \times \vec{B} + \vec{A} \times \vec{C}$$



**FIGURE 1.5**

The direction of  $\mathbf{A} \times \mathbf{B}$  is in the direction of advance of a right-handed screw as  $\mathbf{A}$  is turned into  $\mathbf{B}$ .

## Other Coordinate Systems: Circular and cylindrical coordinates

### Cylindrical coordinates $(\rho, \phi, z)$

$$\vec{P} = \rho_1 \hat{a}_\rho + \phi_1 \hat{a}_\phi + z_1 \hat{a}_z$$

variation:

$$0 \leq \rho < \infty, 0 \leq \phi \leq 2\pi, -\infty \leq z \leq \infty$$

Differential length:

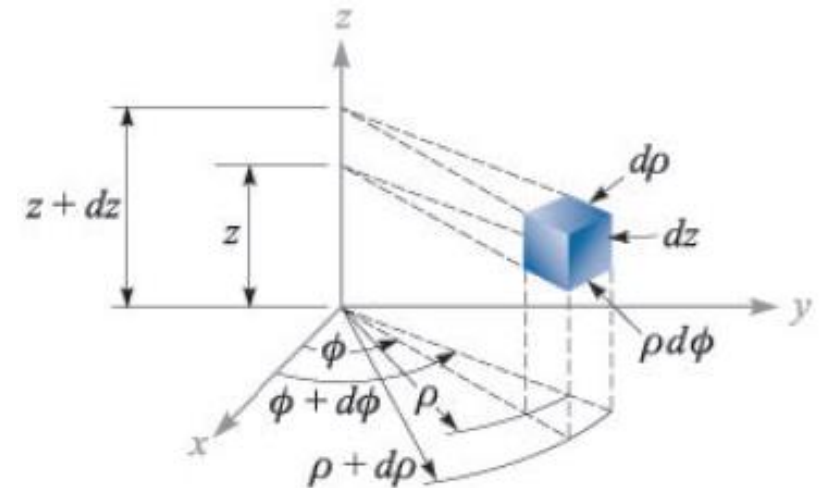
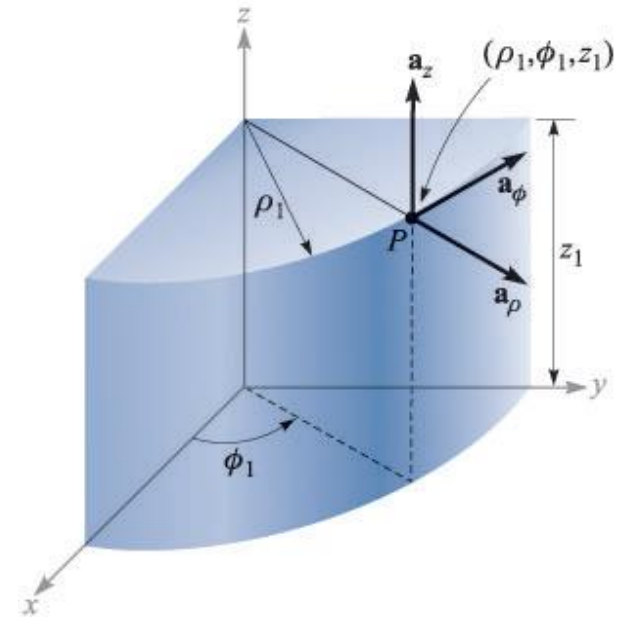
$$d\vec{l} = d\rho \hat{a}_\rho + \rho d\phi \hat{a}_\phi + dz \hat{a}_z$$

Differential area:

$$d\vec{S} = \rho d\phi dz \hat{a}_\rho + d\rho dz \hat{a}_\phi + \rho d\rho d\phi \hat{a}_z$$

Differential Volume:

$$dv = \rho d\rho d\phi dz$$





## Relation between Cylindrical and cartesian coordinates

If I have  $\rho$ ,  $\varphi$  and  $z$

$$X = \rho \cos \varphi$$

$$y = \rho \sin \varphi$$

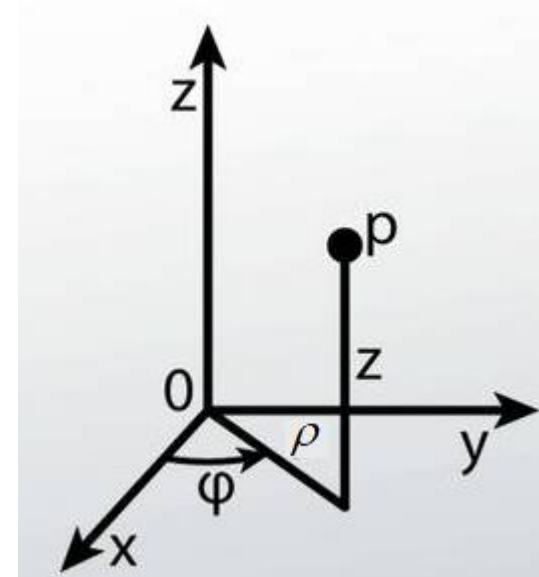
$$Z = z$$

If I have  $x$ ,  $y$  and  $z$

$$\rho = \sqrt{x^2 + y^2}$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right)$$

$$Z = z$$



### Example

Transform the vector  $\mathbf{B} = y\mathbf{a}_x - x\mathbf{a}_y + z\mathbf{a}_z$  into cylindrical coordinates.

**Solution.** The new components are

$$\begin{aligned} B_\rho &= \mathbf{B} \cdot \mathbf{a}_\rho = y(\mathbf{a}_x \cdot \mathbf{a}_\rho) - x(\mathbf{a}_y \cdot \mathbf{a}_\rho) \\ &= y \cos \phi - x \sin \phi = \rho \sin \phi \cos \phi - \rho \cos \phi \sin \phi = 0 \end{aligned}$$

$$\begin{aligned} B_\phi &= \mathbf{B} \cdot \mathbf{a}_\phi = y(\mathbf{a}_x \cdot \mathbf{a}_\phi) - x(\mathbf{a}_y \cdot \mathbf{a}_\phi) \\ &= -y \sin \phi - x \cos \phi = -\rho \sin^2 \phi - \rho \cos^2 \phi = -\rho \end{aligned}$$

Thus,

$$\mathbf{B} = -\rho \mathbf{a}_\phi + z \mathbf{a}_z$$

	$\hat{a}_x$	$\hat{a}_y$	$\hat{a}_z$
$\hat{a}_\rho$	$\cos \varphi$	$\sin \varphi$	$0$
$\hat{a}_\phi$	$-\sin \varphi$	$\cos \varphi$	$0$
$\hat{a}_z$	$0$	$0$	$1$

## Spherical coordinates $(r, \theta, \phi)$

$$\vec{P} = P_r \hat{a}_r + P_\theta \hat{a}_\theta + P_\phi \hat{a}_\phi$$

variation:

$$0 \leq r < \infty, 0 \leq \theta \leq \pi, 0 \leq \phi \leq 2\pi$$

Differential length:

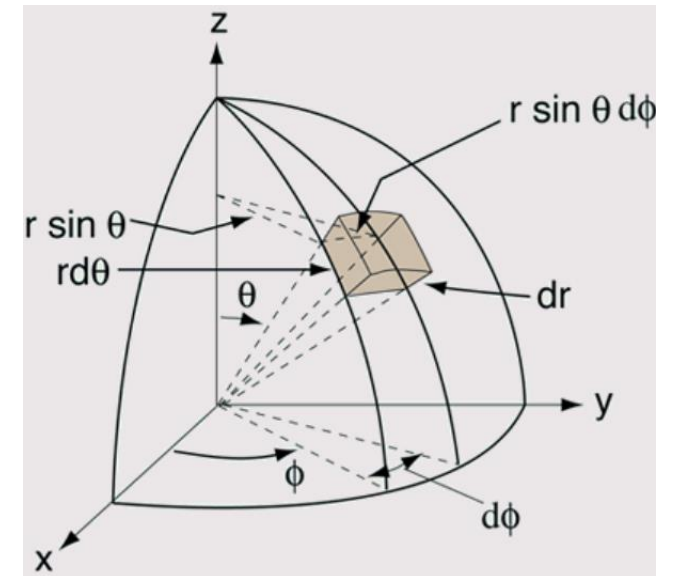
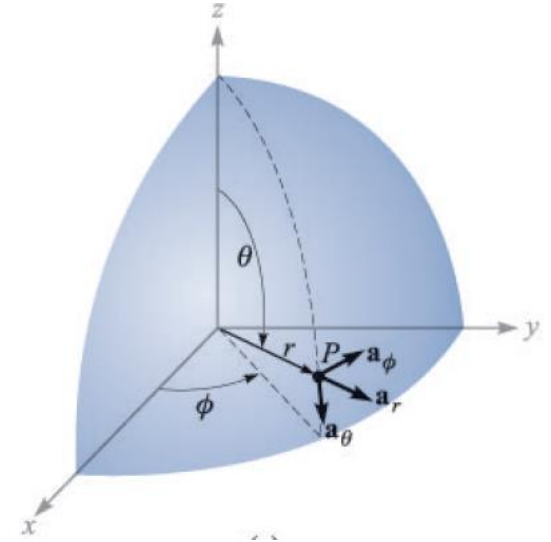
$$d\vec{l} = dr \hat{a}_r + r d\theta \hat{a}_\theta + r \sin \theta d\phi \hat{a}_\phi$$

Differential area:

$$d\vec{S} = r^2 \sin \theta d\theta d\phi \hat{a}_r + r \sin \theta dr d\phi \hat{a}_\theta + rd\theta dr \hat{a}_\phi$$

Differential Volume:

$$dv = r^2 \sin \theta dr d\theta d\phi$$



## Relation between spherical and cartesian coordinates

If I have  $r$ ,  $\theta$  and  $\phi$

$$X = r \sin \theta \cos \phi$$

$$Y = r \sin \theta \sin \phi$$

$$Z = r \cos \theta$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \tan^{-1} \left( \frac{\sqrt{x^2 + y^2}}{z} \right)$$

$$\phi = \tan^{-1} \left( \frac{y}{x} \right)$$

### Example

We illustrate this transformation procedure by transforming the vector field  $\mathbf{G} = (xz/y)\mathbf{a}_x$  into spherical components and variables.

*Solution.*

$$G_r = \mathbf{G} \cdot \mathbf{a}_r = \frac{xz}{y} \mathbf{a}_x \cdot \mathbf{a}_r = \frac{xz}{y} \sin \theta \cos \phi$$

$$= r \sin \theta \cos \theta \frac{\cos^2 \phi}{\sin \phi}$$

$$G_\theta = \mathbf{G} \cdot \mathbf{a}_\theta = \frac{xz}{y} \mathbf{a}_x \cdot \mathbf{a}_\theta = \frac{xz}{y} \cos \theta \cos \phi$$

$$= r \cos^2 \theta \frac{\cos^2 \phi}{\sin \phi}$$

$$G_\phi = \mathbf{G} \cdot \mathbf{a}_\phi = \frac{xz}{y} \mathbf{a}_x \cdot \mathbf{a}_\phi = \frac{xz}{y} (-\sin \phi)$$

$$= -r \cos \theta \cos \phi$$

Collecting these results, we have

$$\mathbf{G} = r \cos \theta \cos \phi (\sin \theta \cot \phi \mathbf{a}_r + \cos \theta \cot \phi \mathbf{a}_\theta - \mathbf{a}_\phi)$$

	$\mathbf{a}_x$	$\mathbf{a}_y$	$\mathbf{a}_z$
$\mathbf{a}_r$	$\sin \theta \cos \phi$	$\sin \theta \sin \phi$	$\cos \theta$
$\mathbf{a}_\theta$	$\cos \theta \cos \phi$	$\cos \theta \sin \phi$	$-\sin \theta$
$\mathbf{a}_\phi$	$-\sin \phi$	$\cos \phi$	0